

Parallel Problem Solving using Hyper-heuristics and Hyflex Framework

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Abstract- Hyper-heuristics comprises a set of approaches with the common goal of automating the design and adaptation of Meta-heuristic methods to solve problems. The primary objective is to produce more generally applicable search methodologies over a given problem domain. The hyper-heuristics will lead to the development of more general solutions that are able to handle a wide range of problem domains on the other hand meta-heuristic approaches are more suitable to a particular problem or a narrow class of problems. Hyper-heuristics are broadly concerned with finding better sequence of heuristic or algorithm applicable in a given situation. Evolutionary algorithms and meta-heuristics approaches have been used to solve a number of optimization problems but their design, however, has become increasingly complex with real world problems, because there are significant number of parameter or algorithm choices involved, and the lack of guidance as to how to proceed when selecting them. To overcome these difficulties a HyFlex framework is used which is a modular and flexible Java class library. It provides a number of problem domain modules, each of which consists of the problem specific algorithm components. In Flex framework only high-level control strategy needs to be implemented and it provides easy-to-use interface used to link problem domain modules.

Keywords: Hyper-heuristics, HyFlex framework, Construction and Perturbation heuristics, Generation hyper-heuristics.

1. Introduction: Hyper-heuristic research aims to achieve the level of generality for the given problem domain. Hyper-heuristics concentrates at reducing the role of human expert in the process of designing computational search methodologies, and thus raise the level of generality in which these methodologies operate (Edmund Burke et al., 2003). Heuristics, meta-heuristics approach to solve computational search problems are becoming complex day by day as these involves number of parameters which are problem dependent and availability of different algorithms available to solve it. Hyper-heuristics tries to overcome these by automating the design and adaptation of heuristic methods, which further results in getting generality of solution in a given problem domain. In 1997 the term hyper-heuristic was first used and a protocol is described that combines several artificial intelligence methods in the context of automated theorem proving (Denzinger, Fuchs, & Fuchs, 1997). In 2000 a term 'heuristics to choose heuristics' was used in the context of combinatorial optimization

A hyper-heuristic is a high-level methodology that operates upon a given a problem instance and a number of low-level heuristics. It then selects and

apply an appropriate low-level heuristic to get generalized solution (Edmund Burke et al., 2003). A number of hyper-heuristic approaches using high-level methodologies, in conjunction with a set of low-level heuristics, applied to different combinatorial problems, have been proposed in the literatures.

As the research in the field of heuristic search automation advances there is a need of reducing the involvement of human expert because of increased complexity of the whole system due number of parameters to set, availability of different algorithms etc. Hyflex is a framework for hyper-heuristics which is a flexible Java class library for designing and testing. HyFlex is a software framework for the development of cross-domain search methodologies. The framework features a common software interface for dealing with different combinatorial optimization problems (Edmund K Burke, Curtois, Hyde, Ochoa, & Vazquez-Rodriguez, 2011). A detailed knowledge of the problem domains is not required for algorithm designer. He/She can concentrate on developing more general purpose solutions for the problem domain. It provides a number of problem domain modules, each of which

encapsulates the problem-specific algorithm components.(Cowling, Kendall, & Soubeiga, 2001). Six hard combinatorial problems are fully implemented: maximum satisfiability, one dimensional bin packing, permutation flow shop, personnel scheduling, traveling salesman and vehicle routing(Edmund K Burke et al., 2011).HyFlex provides an interface to link the problem domain modules in an easy manner.

2. Hyper-heuristics: The term hyper-heuristics has been broadly defined as "heuristics to select heuristics"(Edmund K Burke et al., 2011). Hyper-heuristics operate on a space of actions that modify a solution of a given problem rather than on space of solutions themselves, as is the case of meta-heuristics. Need for new approach arises because meta-heuristics were usually problem specific and required fine tuning of their parameters. So it is necessary to have domain knowledge as well as good knowledge of the applied meta-heuristic(Bilgin, Özcan, & Korkmaz, 2006)(Özcan, Bilgin, & Korkmaz, 2008).Therefore, the reusability of such sophisticated algorithms was often limited. Domain specific control parameters required meant that these algorithms could not have been used on other domain than they were designed for and even different set of constraints in the same domain would mean suboptimal performance and would require very different parameter settings (Edmund Burke et al., 2003).

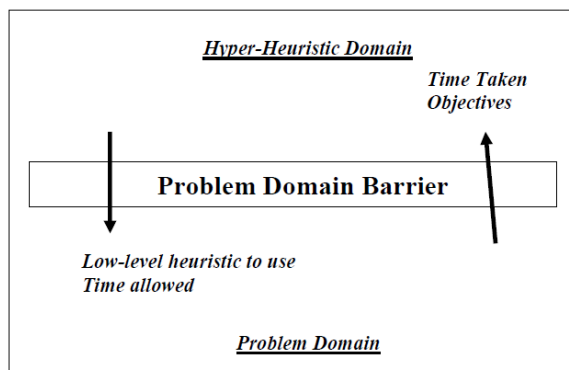


Figure 1 A schematic of separation of high level HH and LLHs

Hyper-heuristic were introduced as a high level approach to select a low level heuristics or combination of low level heuristics that would be most suitable for the problem at hand. The Figure 1 shows the communication of hyper-heuristic high level through the domain barrier by using domain specific evaluation metrics.

Various different classifications of hyper-heuristics have been presented in

literature. majority of these classifications were summarized in (Edmund K Burke et al., n.d.). In it hyper-heuristics are classified on the basis of their learning mechanisms and by the nature of the heuristics search space.

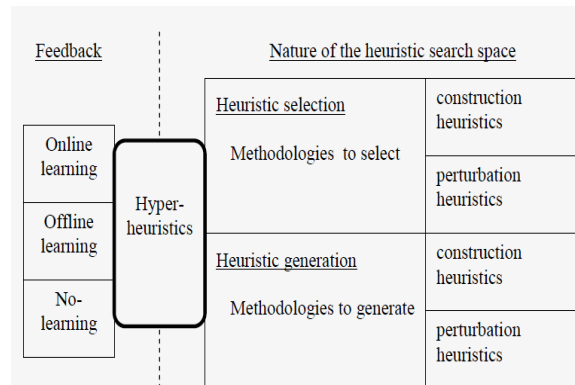


Figure 2 A classification of hyper-heuristic approaches, according to two dimensions (i) the nature of the heuristic search space, and (ii) the source of feedback during learning.

From the learning point of view, three categories were introduced:

- No learning - these algorithms without learning simply follow predetermined sequence of actions that do not reflect the performance on the current problem nor any preceding problems. An example of such technique would be VNS as described in (Hansen & Mladenović, 2001).
- Offline learning - these algorithms use information gathered through training on few problem instances to select the most suitable heuristics for the given problem domain as a whole. Example of this approach is the XCS framework described in (Javier G. Marín-Blázquez, 1998).
- Online learning - these methods use feedback obtained during the execution on a given problem to alter the heuristic selection on the run. Algorithms that use reinforced learning for heuristic selection like (Sim, n.d.) or (E. K. Burke, Kendall, & Soubeiga, 2003) are a good example of this group as well as those using EA to select heuristics like (Kendall, 2003)

Classification by the nature of the heuristic search space introduces two categories:

- Heuristic selection methodologies:
 - Produce combinations of pre-existing:
 - Construction heuristics
 - Perturbation heuristics
- Heuristic generation methodologies:

Generate new heuristic methods using basic components (building-blocks) of:

- Construction heuristics
- Perturbation heuristics

2.1 Construction and Perturbation heuristics

- Construction heuristics - they start with empty solution and they gradually build it until complete solution is found.
- Perturbation heuristics - they can only modify existing solution and include mutational heuristics and hill-climbers or local searchers. These will typically use a randomly generated solution or solution created by construction heuristic as a starting point. Construction heuristics can be only applied when the solution is incomplete, whilst the perturbation heuristics can be applied any time.

2.1.1 Selection constructive hyper-heuristics

In these approaches solutions are built incrementally. It starts with an empty solution, and then gradually constructive heuristics are selected and used to build a complete solution. The hyper-heuristic framework is provided with a set of pre-existing constructive heuristics. The main task is to select the heuristic that is somehow the most suitable for the current problem state. This process continues until the final state has been reached. As there is a natural ending to the construction process when a complete solution is reached.

2.1.2 Selection perturbative hyper-heuristics

These approaches aim through a process of automatically selecting and applying a heuristic. In these approaches heuristics are automatically selected and applied to improve a candidate solution. Online and offline machine learning techniques are useful to the heuristic selection strategies in order to make informed decisions regarding which heuristic to employ at a given step. Wide variety of combinatorial optimization problems have been solved using hyper-heuristic methodologies based on perturbative heuristics.

There are a few studies on the hyper-heuristic methodologies to select perturbative heuristics that perform multi-point search. The majority of proposed approaches conduct a single point search. In a single point search based hyper-heuristic framework, an initial candidate solution

goes through a set of successive stages repeatedly until termination. First, a heuristic (or a subset of heuristics) is selected from a set of low-level perturbative heuristics and then applied to a single candidate solution.

Finally, a decision is made about whether to accept or reject the new solution. A hyper-heuristic to select perturbative heuristics performing single-point search combines two separate components: (i) heuristic selection method and (ii) move acceptance method.

2.1.3 Generation hyper-heuristics

The main feature of these type of hyper-heuristic searches is that a space of heuristics constructed from components rather than a space of complete, pre-defined, heuristics. Heuristic generator may output the new heuristic that produced the solution, and this newly generated heuristic can be potentially reused on new problem instances.

Genetic programming is an evolutionary computation technique that evolves a population of computer programs, and is the most common methodology used to automatically generate heuristics. So genetic programming can be viewed as a hyper-heuristic to generate heuristics.

3. Hyflex framework

Real-world complex optimization problems are successfully handled by evolutionary algorithms and meta-heuristics, but their design however has become increasingly complex. To make these methodologies universally applicable, it is important to provide self-managed systems that can manage and reconfigure themselves 'on the fly'; adapting to the changing problem conditions, based on general rules provided by their users (Edmund K Burke et al., 2011).

To provide such a level of generality, hyper-heuristic frameworks are used. This is a very active area of research where new hyper-heuristics frameworks are emerging. They are classified into different types of hyper-heuristic with the help of shared common features. This field is a sub-field of artificial intelligence, which again is a substantial collection of bio-inspired algorithms (Ryser-welch & Miller, n.d.).

Hyper-heuristics instead of working on a search space of problem solutions, automatically generates an algorithm that solves a problem

more efficiently. It provides at least one solution whenever the algorithm stops but a global optima is not guaranteed to be found with heuristics.

HyFlex was used to support an international research competition: the first Cross-Domain Heuristic Search Challenge. HyFlex (Hyper-heuristic Flexible framework) (Edmund K Burke et al., 2011) is a software framework helping in the development of domain independent search heuristics (hyper-heuristics), and testing across multiple problem domains.

Hyper-heuristics Flexible framework enables the development, testing and comparison of hyper-heuristics. To achieve these goals it uses modularity and the concept of decomposing a heuristic search algorithm into two main parts (Edmund K Burke et al., 2011):

1. A general-purpose part: the algorithm or hyper-heuristic.
2. The problem-specific part: provided by the HyFlex framework.

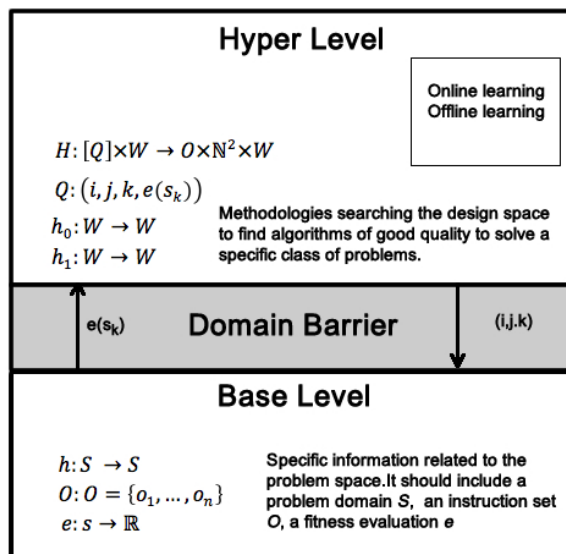


Figure 3 The mathematical model suggested by (Swan, Drake, Ozcan, Goulding, & Woodward, 2013) to represent a hyper-heuristics system.

The motivation of Hyflex was inspired by the two-level hyper heuristic model. “The emphasis of our HyFlex framework lies in providing the algorithm components that are problem specific, thus liberating the algorithm designers needing to know the problem’s domain’s specific details” (Ek Burke, Curtois, & Hyde, 2009)

The algorithm designers only devise new hyper level algorithms; the Base level contains a library of well-known combinatorial problem domains with their benchmarks.

In this context, the low-level heuristic is a set of operators that either brings small or large changes in the problem solutions. These perturbations result in expansion of search to a larger neighborhood and then guarantees better solutions are discovered. The framework structure hides strictly within the domain barrier the problem domain, in order to implement a domain-independent form of hyper-heuristic.

The framework is written in Java which is an object orientation, platform independence and it has automatic memory management. At the highest level, the framework consists of just two abstract classes: **Problem Domain** and **Hyper Heuristic**. The structure of these classes is shown in the class diagram of figure 4.

In the diagram, the signatures adjacent to circles are public methods and fields and the signatures adjacent to diamonds are protected. Abstract methods are denoted by italics and the implementations of these methods are necessarily different for each instantiation of problem domain or hyper-heuristic.

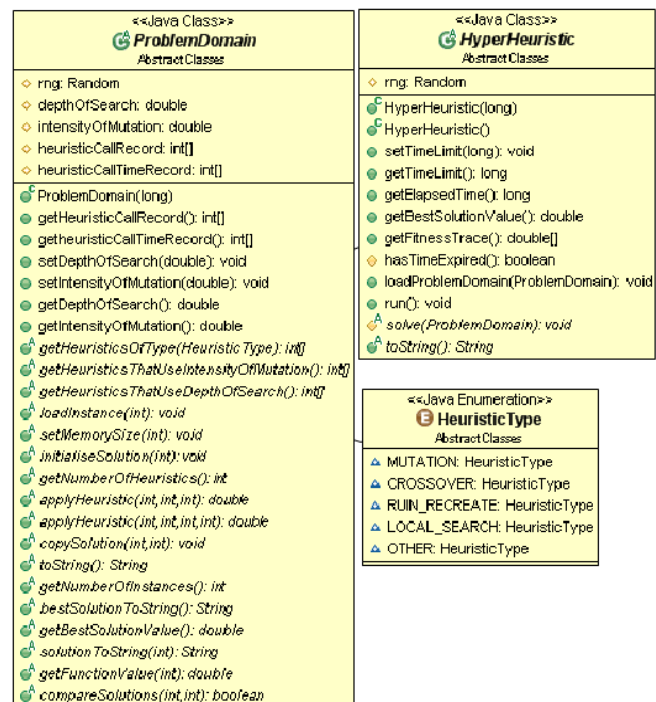


Figure 4 Class-diagram-for-the-HyFlex-framework

3.1 The Problem Domain Class

The Problem Domain class provides the following elements.

- A user-configurable memory (a population) of solutions, which can be managed by the hyper-heuristic through methods such as **setMemorySize** and **copySolution**.
- A routine to randomly initialize solutions, **initialiseSolution(I)**, where *i* is the index of the solution array in the memory.
- A set of problem specific heuristics, which are used to modify solutions. These are called with the **applyHeuristic(i, j, k)** method, where *i* is the index of the heuristic to call, *j* is the index of the solution in memory to modify and *k* is the index in memory where the resulting solution should be placed.
- A varied set of instances that can be easily loaded using the method: **loadInstance(a)**, where *a* is the index of the instance to be loaded.
- A fitness function, which can be called with the **getFunctionValue(i)** method, where *i* is the index of the required solution in the memory. HyFlex problem domains are always implemented as minimization problems, so a lower fitness is always better. The fitness of the best solution found so far in the run can be obtained with the **getBestSolutionValue()** method.
- Two parameters: α and β , ($0 \leq [\alpha, \beta] \leq 1$), which are the 'intensity' of mutation and 'depth of search', respectively, that control the behavior of some search operators.

3.2 The Hyper Heuristic Class

- The **HyperHeuristic** class is designed to allow algorithms which implement this class to be compared and benchmarked across one or more of the problem domains available. Each class must contain a **toString()** method, to give the methodology a name.
- It must also contain a **solve()** method, in which the functionality of the particular methodology is written. The **solve()**

method would normally contain a loop, which continues while the time limit (defined by the user) has not been exceeded.

- In the loop, the code should provide a mechanism for selecting between the available problem-specific heuristics and choose to which solutions in memory to apply the heuristics. This class could choose to work with a memory size of 1 for a single point search, or a large memory could be maintained for a population based approach.
- A hyper-heuristic class automatically records the length of time for which it has been running and this can be monitored through methods such as **TimeExpired()** and **getElapsedTime()**.

4. Limitations of Hyflex framework

- Ability of Hyflex of solving large real-world problems is limited by strict use of templates (Ross, 2014).
- The algorithm designers are required to structure their code with the explicit definitions of the three components.
- The framework seems to only support local search meta-heuristic in the Hyper level, making it very challenging to use Genetic Programming.

5. Discussion and Future work

The hyper-heuristics operates on a search space of heuristics rather than directly on a search space of problem solutions. This feature provides the potential for increasing the level of generality of search methodologies.

Heuristic generation methodologies offer more scope for greater levels of generalization. However, they can be more difficult to implement, when compared with heuristic selection methodologies since they require the decomposition of existing heuristics, and the design of an appropriate framework.

HyFlex is a software framework which enables cross-domain algorithms to be easily developed and reliably compared. It currently provides 6 problem domains, each containing a set of problem instances and search operators to

apply. Therefore, it represents a novel extension of the notion of benchmark for combinatorial optimization. When using HyFlex, researchers can concentrate their efforts on designing their adaptive methodologies, rather than implementing the required set of problem domains.

Different algorithm design ideas have been implemented and tested using HyFlex. Some successful design principles start to emerge such as the use of diversification and intensification phases, the use of reinforcement learning for heuristic selection, adaptation of the heuristic parameters and the use of adaptive acceptance criteria. HyFlex can be extended to include new domains, additional instances and Operators in existing domains and multi-objective and dynamic problems. The current software interface can also be extended to incorporate additional feedback information from the domains to guide the adaptive search controllers.

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